

MP-Bus Data-Pool Values



JR actuator Rotary actuator for butterfly valves

Edition 2024-10 / V1.06



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Data-Pool general notes

General information

- The device supports the MP Data-Pool functional profile. All available data points are managed in a data pool and accessible with MP read/ write commands.
- This document describes all public data pool values of the device.
 It's divided into process values and configuration values.
- The MP Data-Pool functional profile is specified in the MP Cooperation Documentation. The document is provided to Belimo MP-Partners.
- See the technical datasheet for technical information about the device itself.

Identification

The connected type can be identified by its series number:

Prefix	Profile type	Profile category	Туре
2	10	23	JRCABAC

Configuration

Configuration data are not password protected. No Login is required.

Timing of MP-Bus queries

Client implementations typically poll the servers in cycles (MP1, MP2, MP3, ...). Reading all data pool values of this node in one cycle are not recommended, because it would reduce the overall MP-Bus performance.

Recommendation:

- Split up the queries into several cycles (e.g. 3 queries per cycle).
- Adjust repetition rates (reading values) according to the rate of change of the value.
- Prevent from reading unused data pool values.

Signed integer

Signed integers are represented as two's complement.

Example:

Value of ID40 = 1111 1101 1111 $0010_2 = -526_{10}$

Actual value

- = value * scaling factor * unit
- = -526 * 0.01 * unit
- = -5.26 unit

Data-Pool values overview

Process

ID	Name	Access
10	Relative Setpoint [%]	R/W
12	Relative Position [%]	R
13	Absolute Position [°]	R
14	Override Control	R/W
	_ -	=
75	Sensor 1 Value	R
76	Sensor 1 Temperature [°C] **)	R
	<u>-</u>	
82	Sensor 2 Value	R
83	Sensor 2 Temperature [°C] **)	R

^{**)} signed integer

Configuration

ID	Name	Access
117	Setpoint Source	R/W
119	Sensor 1 Type	R/W
120	Sensor 2 Type	R/W
121	Sensor 1 Passive Type	R/W
123	Sensor 2 Passive Type	R/W
	_=	
1001	Malfunction & Service Information	R
	_=	
1052	Maximum Limit [%]	R/W
1057	Bus Watchdog Fail Action	R/W
1058	Timeout for Bus Watchdog [s]	R/W

Definition Access: R = Read, W = Write



All writeable datapoints with ID >100 (configuration data) are persistent and are ${f not}$ supposed to be written on a regular basis.

Data-Pool values

Process data

Description Comments	Unit	Scaling	Values	Size	Access
Relative setpoint The setpoint is related to the position, see also ID 13. Overridden = true, if forced control (bus ID 14, tool and analog forced control) is active	%	0.01	010'000 Default: 0	2	R/W
Relative position Overridden = true, if the gear train is disengaged	%	0.01	010'000	2	R
Absolute position	0	0.01	09'500	2	R
Override control Overrides setpoint with defined values.	_	1	0: None 8: - 1: Open 9: - 2: Close 10: - 3: - 11: - 4: Mid 12: - 5: Max 13: - 6: - Default: 0 7: -	1	R/W
Sensor 1 value Depending on the setting of Sensor 1 type (ID 119) and Sensor 1 passive type (ID 121).	mV 0/1 Ω	1 - 0.01	05'500'000	4	 R
Sensor 1 temperature	°C	0.1	-2'7311'768	2	R
_		_	-	_	_
Sensor 2 value Depending on the setting of Sensor 2 type (ID 120) and Sensor 2 passive type (ID 123).	mV 0/1 Ω	1 - 0.01	05'500'000	4	R
Sensor 2 temperature	°C	0.1	-2'7311'768	2	R
_	_	_	-		_
	Relative setpoint The setpoint is related to the position, see also ID 13. Overridden = true, if forced control (bus ID 14, tool and analog forced control) is active Relative position Overridden = true, if the gear train is disengaged Absolute position Override control Overrides setpoint with defined values.	Comments Relative setpoint % The setpoint is related to the position , see also ID 13. Overridden = true, if forced control (bus ID 14, tool and analog forced control) is active Relative position % Overridden = true, if the gear train is disengaged Absolute position ~ Override control ~ Overrides setpoint with defined values. Foreign (ID 119) and Sensor 1 passive type 0/1 (ID 119) and Sensor 1 passive type 0/1 (ID 121). Sensor 1 temperature °C C Sensor 2 value mV Depending on the setting of Sensor 2 type 0/1 (ID 120) and Sensor 2 passive type 0/1 (ID 123). C Sensor 2 temperature °C	Comments Relative setpoint The setpoint is related to the position , see also ID 13. Overridden = true, if forced control (bus ID 14, tool and analog forced control) is active Relative position % 0.01 Overridden = true, if the gear train is disengaged % 0.01 Absolute position ° 0.01 Override control - 1 Overrides setpoint with defined values. mV 1 - - - Sensor 1 value mV 1 Depending on the setting of Sensor 1 type 0/1 - (ID 119) and Sensor 1 passive type °C 0.1 - - - - Sensor 1 temperature °C 0.1 - - - - Sensor 2 value mV 1 Depending on the setting of Sensor 2 type 0/1 - (ID 120) and Sensor 2 passive type 0 0.01 (ID 123). Sensor 2 temperature °C 0.1	Relative setpoint The setpoint is related to the position , see also ID 13. Overridden = true, if forced control (bus ID 14, tool and analog forced control) is active Relative position Overridden = true, if the gear train is disengaged Mabsolute position Overridden = true, if the gear train is disengaged Ounder the control Overrides setpoint with defined values. Ounder the control Overrides Overrides Overrides Ounder the control Overrides Ounder the control Overrides Ounder the control Ounder t	Relative setpoint The setpoint is related to the position see also D 13.

Configuration data

No.	Description Comments	Unit	Scaling	Values		Size	Access
117	Setpoint Source If Analog (0) then actuator is controlled by analog signal 010 V on wire 3. If Bus (1) then setpoint is controlled via bus.	_	1	0: Analog 1: Bus Default: 0		1	R/W
	_	-	_	_		-	_
119	Sensor 1 type	=	1	0: None 1: Active volt 2: –	3: Passive 4: Switch Default: 0	1	R/W

No.	Description Comments	Unit	Scaling	Values		Size	Access
120	Sensor 2 type	=	1	0: None 1: Active volt 2: –	3: Passive 4: Switch Default: 0	1	R/W
121	Sensor 1 passive type Value selection related to selected units as on ID 150. Only available if ID 119 Sensor 1 type is set to value 3 "Passive".	-	1	0: None 1: PT1000 2: Ni1000EU 3: - 4: -	5: - 6: - 7: NTC10k2 8: NTC10k3 Default: 0	1	R/W
				_			
123	Sensor 2 passive type Value selection related to selected units as on ID 150. Only available if ID 120 Sensor 2 type is set to value 3 "Passive".	-	1	0: None 1: PT1000 2: Ni1000EU 3: - 4: -	5: - 6: - 7: NTC10k2 8: NTC10k3 Default: 0	1	R/W
	_	-	_	_		_	_
1001	Malfunction & service information Value is bit-coded. More than one bit can be set to 1. Not all bits mentioned in the enumeration are used for this product range.	-	1	0: Power fail 1: - 2: - 3: Gear train disengaged / hand crank plugged 4: - 5: Actuator cannot move 6: -	7: - 8: - 9: Watchdog triggered 10: - 11: - 12: - 13: - 14: - 15: -	4	R
			_	_			
1052	Maximum limit Max has to be ≥ 30%	%	0.01	3'00010'000 Default: 0		2	R/W
				_			
1057	Bus watchdog fail action The bus monitoring controls the MP-Bus communication. If neither the Setpoint (ID 10) nor the Override Control (ID 14) is renewed before the Timeout for Bus Watchdog (ID 1058), the actuator is controled by the Bus Watchdog Fail Action. Triggered bus monitoring is indicated in the Malfunction and Service Information (ID 1001).	-	1	0: None 1: Open 2: Close 3: Max 4: – 5: Mid 6: – 7: –	8: - 9: - 10: - 11: - 12: - 13: - Default: 0	1	R/W
1058	Timeout for bus watchdog If no write request is received within the timeout, the device will execute the action defined in ID 1057 (bus watchdog fail action).	S	1	53'600 Default: 120		2	R/W

Definition Access: R = Read, W = Write

All inclusive.

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5-year warranty



On site around the globe



Complete product range



Tested quality



Short delivery times



Comprehensive support

