

**MP<sup>↗</sup>BUS**<sup>®</sup>

## **2-way EPIV V4 DN 15...50**

### **Contents**

Data-Pool General Notes	2
Data-Pool Values Overview	3
Data-Pool Values	4

## Data-Pool General Notes

### General information

- The device supports the MP Data-Pool functional profile. All available data points are managed in a data pool and accessible with MP read/write commands.
- This document describes all public data pool values of the device. It's divided into process values and configuration values.
- The MP Data-Pool functional profile is specified in the MP Cooperation Documentation. The document is provided to Belimo MP-Partners.
- See the technical datasheet for technical information about the device itself.

### Identification

The connected type can be identified by its series number:

Prefix	Profile Type	Profile Category	Type
2	2	35	EP...R2+...

### Configuration

Configuration data are not password protected. No Login is required.

### Timing of MP-Bus queries

Master implementations typically poll the slaves in cycles (MP1, MP2, MP3, ...). Reading all data pool values of this node in one cycle are not recommended, because it would reduce the overall MP-Bus performance

Recommendation:

- Split up the queries into several cycles (e.g. 3 queries per cycle).
- Adjust repetition rates (reading values) according to the rate of change of the value
- Prevent from reading unused data pool values

### Signed integer

#### Example

Signed integers are represented as two's complement.

Value of ID40 = 1111'1101'1111'0010<sub>2</sub> = -526<sub>10</sub>

Actual Value = Value \* Scaling factor \* Unit = -526 \* 0.01 \* °C = **-5.26 °C**



All writeable datapoints with ID >100 (configuration data) are persistent and are not supposed to be written on a regular base.

## Data-Pool Values Overview

	ID	Name	R/W
Process	10	<b>Setpoint [%]</b>	R/W
	11	<b>Command</b>	R/W
	12	Relative Position [%]	R
	13	Absolute Position [°]	R
	14	<b>Override</b>	R/W
	15	Sensor 1 Value [mV] [-]	R
	16	Setpoint Analog [%]	R
	19	Relative Volumetric Flow [%]	R
	20	Absolute Volumetric Flow [l/s]	R
	26	Glycol Concentration [%]	R
	29	Temperature [°C]	R
	51	Total Volume [m³]	R
	110	Malfunction & Service information	R
Configuration	111	<b>Control Mode</b>	R/W
	115	<b>Bus Fail Action</b>	R/W
	116	<b>Communication Watchdog [s]</b>	R/W
	117	<b>Setpoint Source</b>	R/W
	120	<b>Sensor 1 Type</b>	R/W
	125	<b>Vmin [%]</b>	R/W
	129	<b>Vmax [%]</b>	R/W
	133	Vnom [l/s]	R
	200	Meter Serial Number (Part 1)	R
	201	Meter Serial Number (Part 2)	R

**Data-Pool Values****Process Data**

Nr	Description	Unit	Scaling	Values	Size	R/W
10	<b>Setpoint</b> The setpoint refers to the demanded position or flow according to the selected control mode. It is scaled between Min and Max limits.  The setpoint is active, if the setpoint is controlled by bus (Setpoint Source = Bus)	%	0.01	0...10'000	2	R/W
11	<b>Command</b> Initiation of actuator functions for service. After command is sent, value changes back to None (0)	-	-	0: None 1: - 2: Sync	1	R/W
12	Relative Position	%	0.01	0...10'000	2	R
13	Absolute Position	°	0.01	0...9'600	2	R
14	<b>Override Control</b> Overriding the setpoint with defined values			0: None 1: Open Valve 2: Close Valve 3: Min Flow 4: - 5: Max Flow 6: Nom Flow 7: - 8: - 9: - 10: - Motor Stop	1	R/W
15	Sensor 1 Value Current value of sensor 1, depending on setting of "Sensor 1 Type" (ID 120)	mV -	1	0...65'535	2	R
16	Setpoint Analog Shows the setpoint in % if the actuator is controlled by analog signal (ID 117)	%	0.01	0...10'000	2	R
19	Relative Volumetric Flow Related to "Nominal Volumetric Flow" (ID 133)	%	0.01	0...15'000	2	R
20	Absolute Volumetric Flow	l/s	0.01	0...10'000	2	R
26	Glycol Concentration	%	0.01	0...10'000	2	R
29	Temperature	°C	0.01	-2'000...12'000	2	R
51	Total Volume	m <sup>3</sup>	0.01	0...21'474'836	4	R

## Configuration Data

Nr	Description	Unit	Scaling	Values	Size	R/W
110	Malfunction & Service information	-	-	Bit 0: No communication to actuator Bit 1: Gear disengaged Bit 2: Actuator cannot move Bit 3: Reverse flow Bit 4: Flow setpoint not reached Bit 5: Flow with closed valve Bit 6: Actual flow > Vnom Bit 7: Flow measurement error Bit 8: - Bit 9: Integrated temperature error Bit 10: - Bit 11: Freeze warning Bit 12: Glycol detected Bit 13: - Bit 14: - Bit 15: Bus watchdog triggered	2	R
111	<b>Control Mode</b>	-	-	0: Position Control 1: Flow Control 2: -	1	R/W
115	<b>Bus Fail Action</b>  Defines the action in case a communication watchdog is triggered (see ID 116)	-	-	0: None 1: Open Valve 2: Close Valve 3: Max Flow 4: Min Flow 5: - 6: Stop	1	R/W
116	<b>Communication Watchdog</b>  Each datapool access (read or write) will reset the watchdog timer. If the watchdog is triggered the action according to ID 115 will be executed.	s	1	30...3'600 Default: 120	2	R/W
117	<b>Setpoint Source</b>  Defines whether the setpoint is controlled by the analog input signal on wire 3 or the MP-Bus	-	-	0: Analog 1: Bus	1	R/W
120	<b>Sensor 1 Type</b>  If Setpoint Source (ID 117) is analog (Hybrid mode), the Sensor 1 Type can be set to Active (1) to see the Setpoint Analog in mV.	-	-	0: None 1: Active 2: - 3: - 4: Switch	1	R/W
125	<b>Vmin</b>  The min setpoint in % is related to Vnom (ID 133) and considered when Control Mode = Flow Control	%	0.01	0...Vmax	2	R/W
129	<b>Vmax</b>  The max setpoint in % is related to Vnom (ID 133) and considered when Control Mode = Flow Control	%	0.01	2'500...10'000	2	R/W
133	Vnom  Nominal volumetric flow	l/s	0.01	0...10'000	2	R
200	Meter Serial Number (Part 1)	-	-	0...2'147'483'647	4	R
201	Meter Serial Number (Part 2)	-	-	0...2'147'483'647	4	R