

Communicative rotary actuator fail-safe for adjusting dampers with safety function in technical building installations

- Air damper size up to approx. 0.5 m²
- Torque motor 2.5 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Communication via Belimo MP-Bus
- Conversion of sensor signals



Technical data

Electrical data	Nominal voltage	AC/DC 24 V		
	Nominal voltage frequency	50/60 Hz		
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V		
	Power consumption in operation	2.5 W		
	Power consumption in rest position	1 W		
	Power consumption for wire sizing	4 VA		
	Connection supply / control	Cable 1 m, 4x 0.75 mm ²		
	Parallel operation	Yes (note the performance data)		
Data bus communication	Communicative control	MP-Bus		
	Number of nodes	MP-Bus max. 8		
Functional data	Torque motor	2.5 Nm		
	Torque fail-safe	2.5 Nm		
	Operating range Y	210 V		
	Input impedance	100 kΩ		
	Operating range Y variable	Start point 0.530 V		
		End point 2.532 V		
	Operating modes optional	Open/close		
	Position feedback U	210 V		
	Position feedback U note	Max. 0.5 mA		
	Position feedback U variable	Start point 0.58 V		
		End point 2.510 V		
	Position accuracy	±5%		
	Direction of motion motor	selectable with switch L/R		
	Direction of motion variable	electronically reversible		
	Direction of motion fail-safe	selectable by mounting L/R		
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) /		
	Manual override	1 (cw rotation) No		
	Angle of rotation	Max. 95°		
	Angle of rotation note	adjustable starting at 37% in 2.5% steps (with		
		mechanical end stop)		
	Running time motor	150 s / 90°		
	Running time fail-safe	<25 s / 90°		
	Sound power level, motor	50 dB(A)		
	Adaptation setting range	manual		



Technical data

Functional data	Adaptation setting range variable	No action Adaptation when switched on Adaptation after using the rotation switch		
	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%		
	Override control variable	MAX = (MIN + 32%)100% MIN = 0%(MAX – 32%) ZS = MINMAX		
	Mechanical interface	Universal shaft clamp 612.7 mm		
	Position indication	Mechanical		
	Service life	Min. 60'000 fail-safe positions		
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)		
	Degree of protection IEC/EN	IP42		
	EMC	CE according to 2014/30/EU		
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14		
	Hygiene test	According to VDI 6022 Part 1 / SWKI VA 104-01, cleanable and disinfectable, low emission		
	Type of action	Type 1		
	Rated impulse voltage supply / control	0.8 kV		
	Pollution degree	3		
	Ambient humidity	Max. 95% RH, non-condensing		
	Ambient temperature	-3050°C [-22122°F]		
	Storage temperature	-4080°C [-40176°F]		
	Servicing	maintenance-free		
Weight	Weight	0.68 kg		

Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.



Product features

Operating mode

The actuator moves the damper to the operating position at the same time as tensioning the return spring. The damper is turned back to the fail-safe position by spring force when the supply voltage is interrupted.

Conventional operation:

The actuator is connected with a standard control signal of 0...10 V and drives to the position defined by the control signal. Measuring voltage U serves for the electrical display of the damper position 0...100% and as control signal for other actuators.

Operation on Bus:

The actuator receives its digital control signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Converter for sensors

Connection option for a sensor (active sensor or switching contact). The MFT actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parametrisable actuators

The factory settings cover the most common applications. Single parameters can be modified with Belimo Assistant 2 or ZTH EU.

Simple direct mounting

Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the control signal.

NO	NC	
L 🚳	R∙⊚	
20		
Y = 0	Y = 0	A – AB = 0%
C.	\bigcap	V - VD = 0%

Adaptation and synchronisation

An adaptation can be triggered manually by switching the direction of rotation switch from the left to the right twice within 5s or with the PC-Tool. Both mechanical end stops are detected during the adaptation (entire setting range). Automatic synchronisation after actuating the direction of rotation switch once is programmed. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the control signal.

A range of settings can be made using Belimo Assistant 2.

Accessories

Tools	Description	Туре	
	Service tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU	
	Service tool for wired and wireless setup, on-site operation, and troubleshooting.	Belimo Assistant 2	
	Adapter for Service-Tool ZTH	MFT-C	
Electrical accessories	Description	Туре	
	Signal converter voltage/current 100 kΩ 420 mA, Supply AC/DC 24 V	Z-UIC	







Accessories

Electrical installation

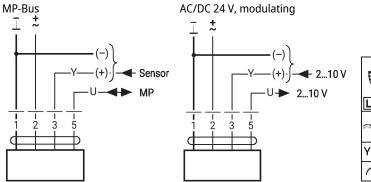


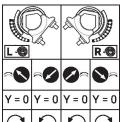
Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

Wire colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange



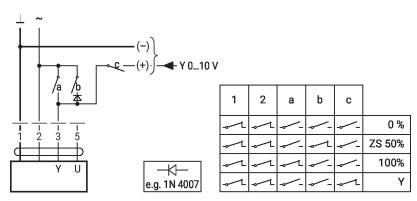




Further electrical installations

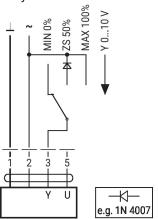
Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts



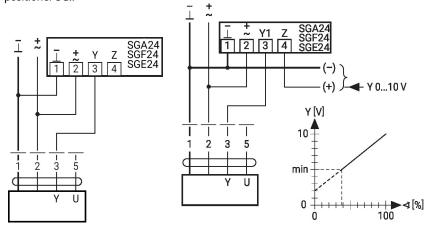
rotary switch

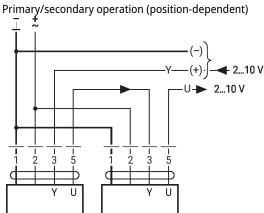
Override control with AC 24 V with



Control remotely 0...100% with positioner SG..

Minimum limit with positioner SG..



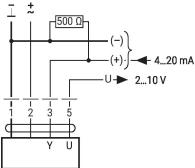


TF24-MFT

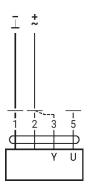


Functions with basic values (conventional mode)

Control with 4...20 mA via external resistor



Functional check



Procedure

- 1. Connect 24 V to connections 1 and 2
- 2. Disconnect connection 3:
- With direction of rotation 0:

Actuator rotates to the left

- With direction of rotation 1:

Actuator rotates to the right

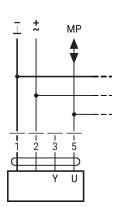
- 3. Short-circuit connections 2 and 3:
- Actuator runs in opposite direction

Caution:

The operating range must be set to DC 2...10 V. The 500 Ohm resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V.

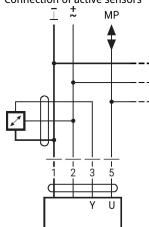
MP-Bus

Connection on the MP-Bus



Max. 8 MP-Bus nodes

Connection of active sensors



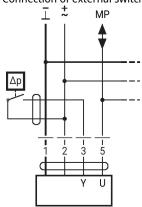
- Supply AC/DC 24 V
- Output signal 0...10 V (max. 0...32 V)
- Resolution 30 mV



Further electrical installations

MP-Bus

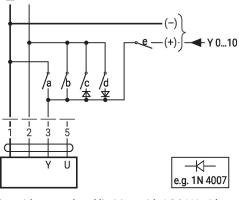
Connection of external switching contact



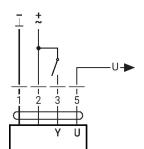
- Switching current 16 mA @ 24
- Start point of the operating range must be parametrised on the MP actuator as ≥0.5 V

Functions with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts

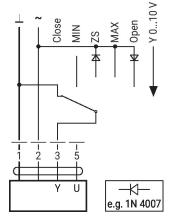


V								
•	1	2	а	b	С	d	е	
	⊸ \	→\L	⊸~L	<u>~</u> _	<u>~</u> _	⊸ -	~	Close
	↓	↓	\	-	\	→ -	-	MIN
	↓	↓ L	-	→	⊸ L	→	→	ZS
	₹	¥	\	¥	\- \-	\- \-	\	MAX
	7	√L	\- -	-	- -	√L	-	Open
	~L	~L	<u>→</u> _	-		⊸ _	→~L	Υ



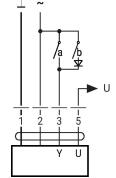
Control open/close

Override control and limiting with AC 24 V with rotary switch

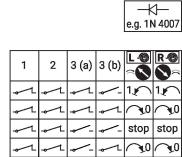


Caution:

The "Close" function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

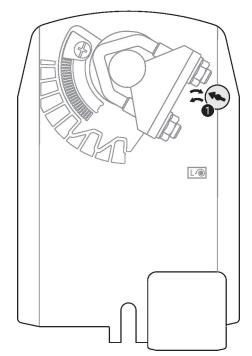


Control 3-point with AC 24 V





Operating controls and indicators



1 MP addressing

Move direction of rotation switch in opposite position and backwards (within 4 seconds)

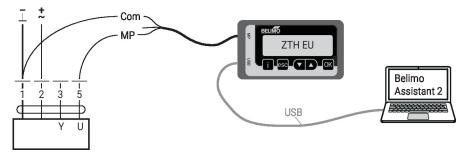
Service

Wired connection

The actuator can be parametrised by ZTH EU via terminal connection.

For extended parametrisation the PC tool can be connected.

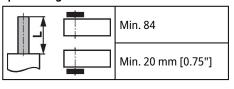
Connection ZTH EU / Belimo Assistant 2





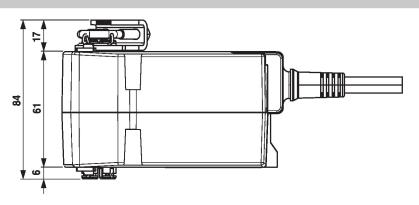
Dimensions

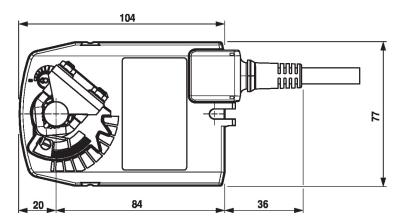




Clamping range

01	♦1		
612.7	612.7		





Further documentation

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology
- Quick Guide Belimo Assistant 2

Application notes

• For digital control of actuators in VAV applications patent EP 3163399 must be considered.