

# Communicative rotary actuator with fail-safe for ball valves

- Torque motor 10 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Communication via Belimo MP-Bus
- Conversion of sensor signals
- Deenergised closed (NC)
- PWIS/LABS-compliant according to VDMA 24364

**Electrical data** 

Data bus communication

**Functional data** 





# Technical data

Nominal voltage	AC/DC 24 V			
Nominal voltage frequency	50/60 Hz			
Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V			
Power consumption in operation	7 W			
Power consumption in rest position	3.5 W			
Power consumption for wire sizing	9.5 VA			
Connection supply / control	Cable 1 m, 4x 0.75 mm <sup>2</sup>			
Parallel operation	Yes (note the performance data)			
Communicative control	MP-Bus			
Number of nodes	MP-Bus max. 8			
Torque motor	10 Nm			
Torque fail-safe	10 Nm			
Operating range Y	210 V			
Input impedance	100 kΩ			
Operating range Y variable	Start point 0.530 V End point 2.532 V			
Operating modes optional	Open/close 3-point (AC only) Modulating (DC 032 V)			
Position feedback U	210 V			
Position feedback U note	Max. 0.5 mA			
Position feedback U variable	Start point 0.58 V End point 2.510 V			
Position accuracy	±5%			
Direction of motion motor	Y = 0 (0 V = A – AB = 0%)			
Direction of motion fail-safe	Deenergised NC, valve closed (A – AB = 0%)			
Direction of motion note	for valves with L-bore (A – AB = 100%)			
Manual override	by means of hand crank and locking switch			
Running time motor	90 s / 90°			
Running time motor variable	40150 s			
Running time fail-safe	<20 s @ -2050°C / <60 s @ -30°C			
Sound power level, motor	45 dB(A)			
Adaptation setting range	manual (automatic on first power-up)			
Adaptation setting range variable	No action Adaptation when switched on Adaptation after using the hand crank			





Technical data			
Functional data	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%	
	Override control variable	MAX = (MIN + 33%)100% MIN = 0%(MAX - 33%) ZS = MINMAX	
	Position indication	Mechanical	
	Service life	Min. 60'000 fail-safe positions	
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)	
	Power source UL	Class 2 Supply	
	Degree of protection IEC/EN	IP54	
	Degree of protection NEMA/UL	NEMA 2	
	Enclosure	UL Enclosure Type 2	
	EMC	CE according to 2014/30/EU	
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14	
	UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1	
		The UL marking on the actuator depends on the production site, the device is UL-compliant in any case	
	PWIS/LABS-conformity	According to VDMA 24364 (test class C1) Approved for use in zone II Cleaning with low-pressure plasma treatment	
	Type of action	Type 1.AA	
	Rated impulse voltage supply / control	0.8 kV	
	Pollution degree	3	
	Ambient humidity	Max. 95% RH, non-condensing	
	Ambient temperature	-3050°C [-22122°F]	
	Storage temperature	-1040°C [14104°F]	
	Servicing	maintenance-free	

2.0 kg

Weight Weight



### Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- · Cables must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.
- PWIS/LABS-conformity is guaranteed as long as the packaging is unopened. Once the PWIS/ LABS-compliant packaging has been opened, the proper handling of the products is the responsibility of the customer. PWIS/LABS-conformity of unopened products is guaranteed for a period of one year after cleaning, provided they are handled properly, professionally and cleanly. Proof of proper, professional and clean handling is the responsibility of the purchaser. Ensure that the required cleanliness of the products is maintained. Do not touch the products with bare hands. Belimo accepts no liability for the consequences resulting from the contamination of a product caused by the customer.

### **Product features**

### Operating mode

Conventional operation:

The actuator is connected with a standard control signal 0...10 V. The actuator moves the valve to the operating position at the same time as tensioning the return spring. The valve is turned back to the fail-safe position by spring force when the supply voltage is interrupted. Operation on Bus:

The actuator receives its digital control signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

#### Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

#### Parametrisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo service tools MFT-P or ZTH EU.

#### Simple direct mounting

Simple direct mounting on the ball valve with only one screw. The mounting orientation in relation to the ball valve can be selected in 90° steps.

### Manual override

By using the hand crank the valve can be operated manually and engaged with the locking switch at any position. Unlocking is carried out manually or automatically by applying the operating voltage.

# Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

### Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaptation, which is when the operating range and position feedback adjust themselves to the mechanical setting range.

The actuator then moves into the position defined by the control signal.

Factory setting: Y2 (counter-clockwise rotation).



### **Product features**

### Adaptation and synchronisation

An adaptation can be triggered manually by pressing the "Adaptation" button or with the PC-Tool. Both mechanical end stops are detected during the adaptation (entire setting range). Automatic synchronisation after actuating the hand crank is programmed. The synchronisation is in the home position (0%).

A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

### **Accessories**

Tools	Description	Туре			
	Service tool, with ZIP-USB function, for parametrisable and	ZTH EU			
	MFT-P				
	Adapter for Service-Tool ZTH				
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN			
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN			
Electrical accessories	Description	Туре			
	MP-Bus power supply for MP actuators	ZN230-24MP			
Gateways	Description	Туре			
	Gateway MP to BACnet MS/TP	UK24BAC			
	Gateway MP to Modbus RTU	UK24MOD			

### **Electrical installation**



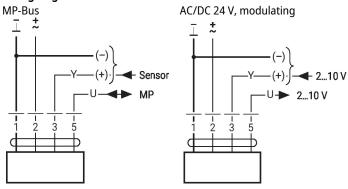
Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

### Wire colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

### Wiring diagrams

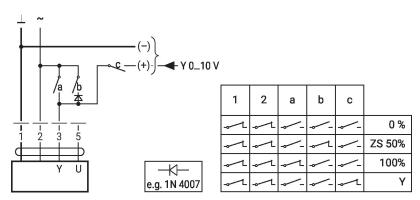




# Further electrical installations

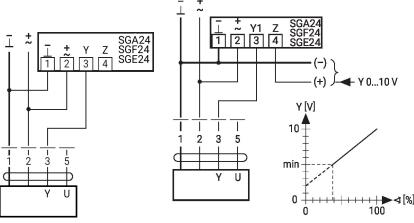
# Functions with basic values (conventional mode)

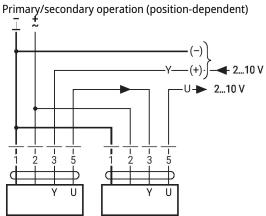
Override control with AC 24 V with relay contacts



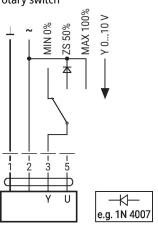
Control remotely 0...100% with positioner SG..

Minimum limit with positioner SG..





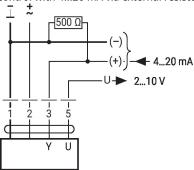
Override control with AC 24 V with rotary switch





### Functions with basic values (conventional mode)

Control with 4...20 mA via external resistor

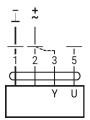


Functional check

# Caution:

The operating range must be set to DC 2...10 V.

The 500 Ohm resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V.



### Procedure

- 1. Connect 24 V to connections 1 and 2
- 2. Disconnect connection 3:
- with direction of rotation L:

Actuator rotates to the left

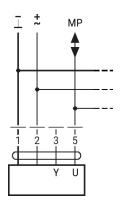
- with direction of rotation R:

Actuator rotates to the right

- 3. Short-circuit connections 2 and 3:
- Actuator runs in opposite direction

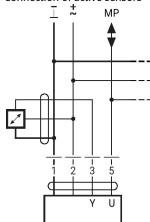
# Functions with specific parameters (Parametrisation necessary)

Connection on the MP-Bus



Max. 8 MP-Bus nodes

### Connection of active sensors

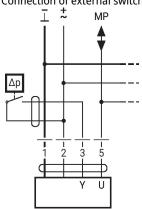


- Supply AC/DC 24 V
- Output signal 0...10 V (max. 0...32 V)
- Resolution 30 mV

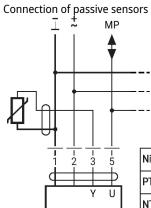


# Functions with specific parameters (Parametrisation necessary)

Connection of external switching contact



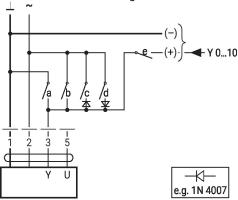
- Switching current 16 mA @ 24
- Start point of the operating range must be parametrised on the MP actuator as ≥0.5 V



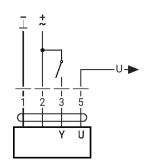
Ni1000 -28+98°C		8501600 Ω <sup>2)</sup>	
PT1000	−35+155°C	8501600 Ω <sup>2)</sup>	
NTC	-10+160°C 1)	200 Ω60 kΩ <sup>2)</sup>	

- 1) Depending on the type
- 2) Resolution 1 Ohm Compensation of the measured value is recommended

Override control and limiting with AC 24 V with relay contacts



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٧	1	2	а	b	С	d	е	
	⊸~L	→\L	⊸~L	<u>~</u> _	<u>~</u> _	<b>⊸</b> -	~	Close
	⊸/L	→\L	<b>⊸</b>	<b>⊸</b> _	- <del></del> -	<b>⊸</b>	<b>→</b>	MIN
	→\L	<b>↓</b> L	<b>-</b>	<b>→</b>	<b>⊸</b> L	<b>⊸</b> -	<b>→</b>	ZS
	¥	¥	\	¥	\- \-	\- \-	<b>\</b>	MAX
	√L	√L	\-  -	<b>→</b>	- -	√L	<b>-</b>	Open
	<b>⊸</b> L	⊸_L	<u></u>	<u></u>	<u>~_</u>		→_L	Υ



Control open/close

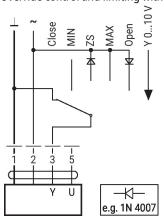


### **Further electrical installations**

# Functions with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with rotary switch

Control 3-point with AC 24 V

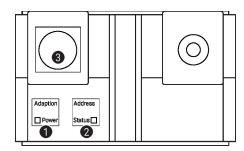


#### Caution:

The "Close" function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

1	2	3		
~L	↓ L		₹	₹
⊸^L	<b>↓</b> L	→_L	<b>±</b>	Ŧ

# **Operating controls and indicators**



# 1 Membrane key and LED display green

Off: No power supply or malfunction

On: In operation

Press button: Triggers angle of rotation adaptation, followed by standard mode

### 2 Membrane key and LED display yellow

Off: Standard mode

On: Adaptation or synchronisation process active

Flickering: MP-Bus communication active

Flashing: Request for addressing from MP client

Press button: Confirmation of the addressing

### 3 Service plug

For connecting parametrisation and service tools

# **Operating elements**

The manual override, locking switch and direction of rotation switch elements are available on both sides



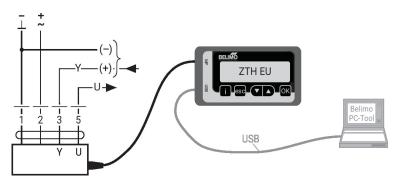
# Service

### **Tool connection**

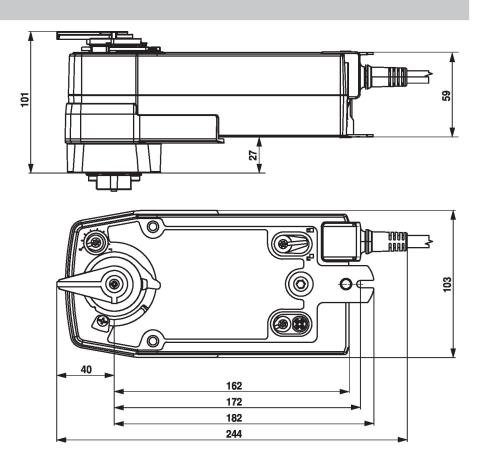
The actuator can be parametrised by ZTH EU via the service socket.

For an extended parametrisation the PC tool can be connected.

# Connection ZTH EU / PC-Tool



# **Dimensions**



### **Further documentation**

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology
- The complete product range for water applications
- Data sheets for ball valves
- Installation instructions for actuators and/or ball valves
- General notes for project planning