

e actuator with fail-

MP² BUS

Communicative globe valve actuator with failsafe for 2-way and 3-way globe valves

- Actuating force 2000 N
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Stroke 32 mm
- Communication via Belimo MP-Bus
- Conversion of sensor signals



Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
	Power consumption in operation	5 W
	Power consumption in rest position	2 W
	Power consumption for wire sizing	9.5 VA
	Connection supply / control	Terminals with cable 1 m, 4x 0.75 mm ²
		(Terminal 4 mm ²)
	Parallel operation	Yes (note the performance data)
Data bus communication	Communicative control	MP-Bus
	Number of nodes	MP-Bus max. 8
Functional data	Actuating force motor	2000 N
	Operating range Y	210 V
	Input impedance	100 kΩ
	Operating range Y variable	Start point 0.530 V
		End point 2.532 V
	Operating modes optional	Open/close
		3-point (AC only) Modulating (DC 032 V)
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point 0.58 V
		End point 2.510 V
	Setting fail-safe position	Stem 0100%, adjustable (POP rotary knob)
	Bridging time (PF)	2 s
	Bridging time (PF) variable	010 s
	Position accuracy	±5%
	Manual override	with push-button
	Stroke	32 mm
	Running time motor	150 s / 32 mm
	Running time motor variable	90150 s
	Running time fail-safe	35 s / 32 mm
	Sound power level, motor	60 dB(A)
	Sound power level, fail-safe	60 dB(A)
	Adaptation setting range	manual (automatic on first power-up)





Technical data

Override control variableMAX = (MIN + 33) ZS = MINMAXPosition indicationMechanical, 532Safety dataProtection class IEC/ENIII, Safety Extra-Lu Power source ULPower source ULClass 2 SupplyDegree of protection IEC/ENIP54Degree of protection NEMA/ULNEMA 2HousingUL Enclosure TypeEMCCE according to 2Certification IEC/ENIEC/EN 60730-1 aUL ApprovalcULus according to and CAN/CSA E60 The UL marking of the production sit in any caseType of actionType 1.AARated impulse voltage supply / control0.8 kVPollution degree3Ambient humidityMax. 95% RH, nor Ambient temperatureMeight3.8 kgWeight3.8 kgTermsAbbreviationsPOP = Power off p CPO = Controlled	switched on pushing the manual override
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Weight 3.8 kg Terms Abbreviations POP = Power off p CPO = Controlled	76°F]
TermsAbbreviationsPOP = Power off pCPO = Controlled	<u>;</u>
CPO = Controlled	
safe PF = Power fail de	oosition / fail-safe position power off / controlled fail- elay time / bridging time

Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The switch for changing the direction of motion and so the closing point may be adjusted only by authorised specialists. The direction of motion is critical, particularly in connection with frost protection circuits.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- · The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

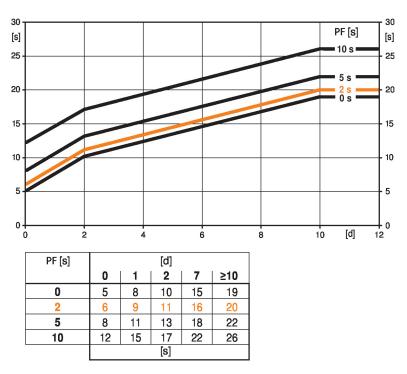


Product features

Operating mode	Conventional operation:
	The actuator is connected with a standard control signal of 010 V and moves to the position defined by the control signal at the same time as the integrated capacitors are loaded.
	Interrupting the supply voltage causes the valve to be moved to the selected fail-safe position by means of stored electrical energy.
	Operation on Bus:
	The actuator receives its digital control signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.
Pre-charging time (start up)	The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset fail-safe position.
	The duration of the pre-charging time depends mainly on following factors:
	Duration of the newer failure

- Duration of the power failure
- PF delay time (bridging time)

Typical pre-charging time



[d] = Power failure in days [s] = Pre-charging time in seconds PF[s] = Bridging time Calculation example: Given a power failure of 3 days and a bridging time (PF) set at 5 s, the actuator requires a pre-charging time of 14 s after the power has been reconnected (see graphic).

Delivery condition (capacitors)

The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 20 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

Bridging time

Power failures can be bridged up to a maximum of 10 s.

In the event of a power failure, the actuator will remain stationary in accordance with the set bridging time. If the power failure is greater than the set bridging time, the actuator will move into the selected fail-safe position.

The bridging time set at the factory is 2 s. It can be modified on site in operation by means of the Belimo service tool MFT-P.

Settings: The rotary knob must not be set to the "Tool" position!

For retroactive adjustments of the bridging time with the Belimo service tool MFT-P or with the ZTH EU adjustment and diagnostic device only the values need to be entered.



Product features	
Setting fail-safe position (POP)	The rotary knob fail-safe position can be used to adjust the desired fail-safe position from 0100% in 10% increments. The rotary knob refers to the adapted or programmed height of stroke. In the event of a power failure, the actuator will move to the selected fail-safe position, taking into account the bridging time (PF) of 2 s set at the factory.
	Settings: The rotary knob must be set to the «Tool» position for retroactive settings of the fail- safe position with the Belimo service tool MFT-P. Once the rotary knob is set back to the range 0100%, the manually set value will have positioning authority.
Converter for sensors	Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.
Parametrisable actuators	The factory settings cover the most common applications. Single parameters can be modified with Belimo Assistant 2 or ZTH EU.
Simple direct mounting	Simple direct mounting on the globe valve by means of form-fit hollow clamping jaws. The actuator can be rotated by 360° on the valve neck.
Manual override	Manual control with push-button possible - temporary. The gear train is disengaged and the actuator decoupled for as long as the button is pressed.
	The stroke can be adjusted by using a hexagon socket screw key (5 mm), which is inserted into the top of the actuator. The stem extends when the key is rotated clockwise.
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Home position	Factory setting: Actuator stem is retracted.
	When valve-actuator combinations are shipped, the direction of motion is set in accordance with the closing point of the valve.
	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaptation, which is when the operating range and position feedback adjust themselves to the mechanical setting range.
	The actuator then moves into the position defined by the control signal.
Adaptation and synchronisation	An adaptation can be triggered manually by pressing the "Adaptation" button or with Belimo Assistant 2. Both mechanical end stops are detected during the adaptation (entire setting range).
	Automatic synchronisation after pressing the manual override button is parametrised. The synchronisation is in the home position (0%).
	The actuator then moves into the position defined by the control signal.
	A range of settings can be made using Belimo Assistant 2.
Setting direction of motion	When actuated, the direction-of-stroke switch changes the direction of motion in normal operation. The direction-of-stroke switch has no influence on the fail-safe position that has been set.
Accessories	

Accessories

Tools	Description	Туре
	Service tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU
	Service tool for wired and wireless setup, on-site operation, and troubleshooting.	Belimo Assistant 2
	Adapter for Service-Tool ZTH	MFT-C
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN



Electrical accessories	Description	Туре
	Auxiliary switch 2x SPDT add-on	S2A-H
	MP-Bus power supply for MP actuators	ZN230-24MF
Gateways	Description	Туре
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to Modbus RTU	UK24MOD

Electrical installation

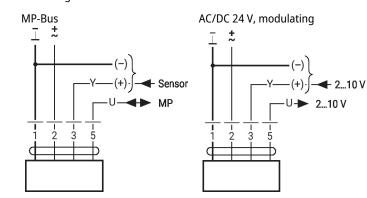
Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

Direction of stroke switch factory setting: Actuator stem retracted (**△**).

Wire colours:

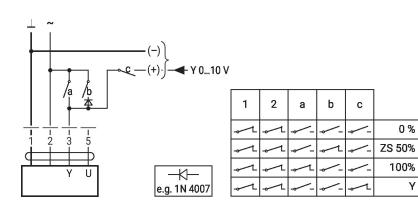
- 1 = black 2 = red
- 3 = white
- 5 = orange

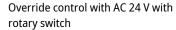


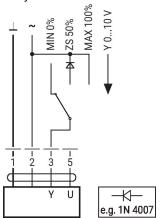
Further electrical installations

Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts



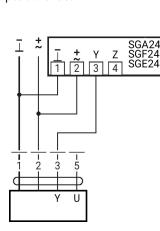


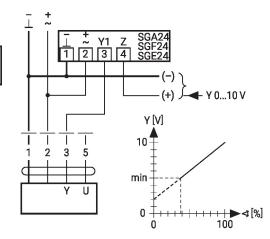




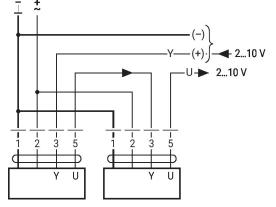
Functions with basic values (conventional mode)

Control remotely 0...100% with Minimum limit with positioner SG..

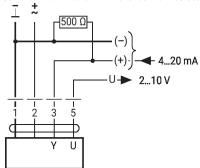




Primary/secondary operation (position-dependent) $\overline{1}$



Control with 4...20 mA via external resistor



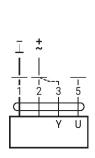
Caution:

The operating range must be set to DC 2...10 V. The 500 Ohm resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V.



Functions with basic values (conventional mode)

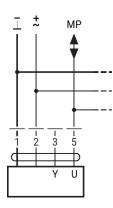
Functional check

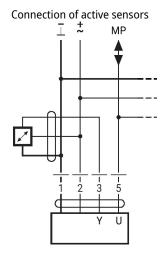


Procedure

MP-Bus

Connection on the MP-Bus



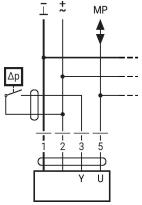


• Supply AC/DC 24 V • Output signal 0...10 V (max.

0...32 V)

• Resolution 30 mV

Connection of external switching contact \overline{T}



• Switching current 16 mA @ 24 V

Max. 8 MP-Bus nodes

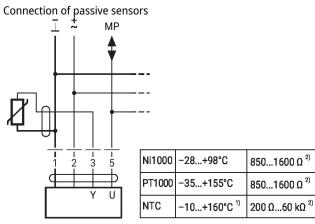
• Start point of the operating range must be parametrised on the MP actuator as ≥0.5 V



Technical data sheet

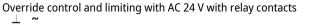
Further electrical installations

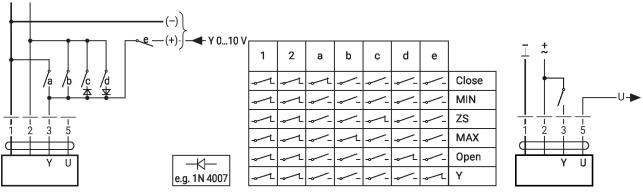




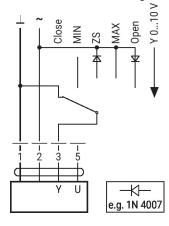
1) Depending on the type 2) Resolution 1 Ohm Compensation of the measured value is recommended

Functions with specific parameters (Parametrisation necessary) Override control and limiting with AC 24 V with relay contacts





Override control and limiting with AC 24 V with rotary switch

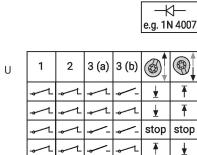


Caution:

The "Close" function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

	/a /b ↓ ¥	
		U
⊈	Y U	

Control 3-point with AC 24 V



Control open/close



Operating controls and indicators

U	Direction of stroke	e switch
	Switch over:	Direction of stroke changes
2	Cover, POP button	n
3	POP button	
	Scale for manual a	adjustment
	Position for adjust	tment with tool
6	Service plug	
	For connecting pa	arametrisation and service tools
	Manual override b	button
	Press button:	Gear train disengages, motor stops, manual override possible
	Release button:	Gear train engages, standard mode
	Push-button (LED	yellow)
3 Status Power 9 Address Adapion	Press button:	Acknowledgment of addressing
	Push-button (LED	green)
	Press button:	Triggers stroke adaptation, followed by standard mode
	Manual override	
	Clockwise:	Actuator stem extends
	Counterclockwise	e: Actuator stem retracts
	LED displays	

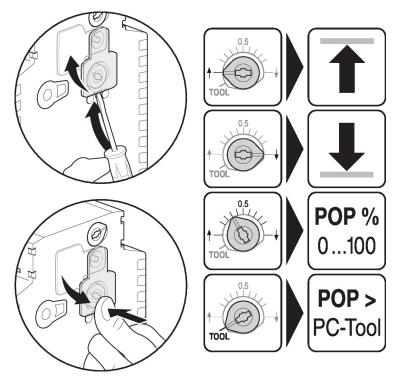
yellow 8	green 9	Meaning / function	
Off	On	Operation OK	
Off	Flashing	POP function active	
On	Off	Fault	
Off	Off	Not in operation	
On	On	Adaptation process active	
Flickering	On	MP-Bus communication active	



Technical data sheet

Operating controls and indicators

Setting fail-safe position (POP)



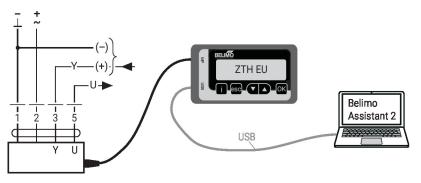
Service

Wired connection

tion The device can be parametrised by ZTH EU via the service socket.

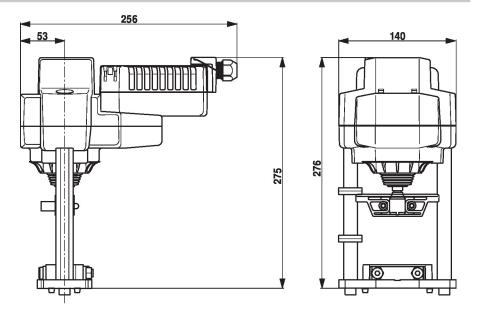
For an extended parametrisation, Belimo Assistant 2 can be connected.

Connection ZTH EU / Belimo Assistant 2





Dimensions



Further documentation

- The complete product range for water applications
- Installation instructions for actuators and/or globe valves
- Data sheets for globe valves
- Notes for project planning 2-way and 3-way globe valves
- General notes for project planning
- Tool connections
- Introduction to MP-Bus Technology
- Overview MP Cooperation Partners
- Quick Guide Belimo Assistant 2